

National Tsunami Hazards Mitigation Program - Benchmarking Workshop

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Talk

- SPH and Neutrino SPH
- Benchmark Problems and Setups
- Discussion of our approach
- Conclusions

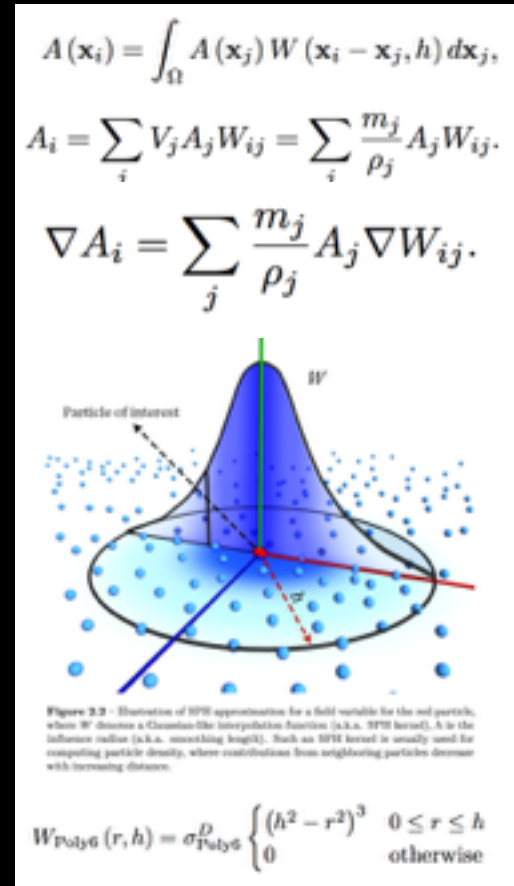
SPH

- SPH - designed for solving astrophysical problems (Gingold & Monaghan) - 1977
- Integral representation of field variables with smoothing kernels.
- Fluid equations become

$$m \frac{d\mathbf{v}}{dt} = \underbrace{-V \nabla p}_{F_{\text{pressure}}} + \underbrace{V \mu \nabla^2 \mathbf{v}}_{F_{\text{viscosity}}} + \underbrace{V \mathbf{f}}_{F_{\text{external}}},$$

- Volume conservation satisfied using pressure forces.
 - Pressures dependent on speed of sound.
- Needs neighborhood search
- Density computed by

$$\rho_i = \sum_j m_j W_{ij}.$$



Neutrino - SPH

- Compact Hashing technique for nearest neighbor search.
- Uses Implicit Incompressible SPH (IISPH) - Details (<http://www.naadir.tk/phd-thesis>)
 - SPH approximation of the continuity equation to obtain discretized form of the poisson equation for pressure.
 - Relaxed Jacobi solver. (Parallel)

$$\frac{\rho_i(t + \Delta t) - \rho_i(t)}{\Delta t} = \sum_j m_j [\mathbf{v}_i(t + \Delta t) - \mathbf{v}_j(t + \Delta t)] \cdot \nabla W_{ij}(t).$$

- Viscosity - Monaghan's Method.
- Rigid Fluid coupling boundary particles

SPH

- Artificial Viscosity
 - Based on Von Neumann-Richmyer artificial viscosity (1950)

$$\mathbf{F}_i^v = -m_i \sum_j m_j \Pi_{ij} \nabla W_{ij},$$

$$\Pi_{ij} = -\nu \left(\frac{\min(\mathbf{v}_{ij} \cdot \mathbf{x}_{ij}, 0)}{|\mathbf{x}_{ij}|^2 + \epsilon h^2} \right),$$

$$\nu = \frac{2\alpha h c_s}{\rho_i + \rho_j}$$

- Solid Boundary Treatment
 - Pressure forces applied from boundary particles to fluid particles
 - Boundary viscosity

$$\mathbf{F}_{f_i \leftarrow b_j}^v = -m_{f_i} \Psi_{b_j}(\rho_{0_i}) \Pi_{ij} \nabla W_{ij},$$

$$\nu = \frac{\sigma h c_s}{2\rho_{f_i}},$$

- Adaptive Time step - Semi Implicit / Euler-Cromer Integration

Density/Pressure Computation

- Density.
 - Based on Monaghan 05 - SPH - Reports on Progress of Physics.
 - Conserves Mass
 - Underestimated densities at fluid interfaces are handled by special handling Rigid/Fluid/Air boundaries causing clumping of particles.

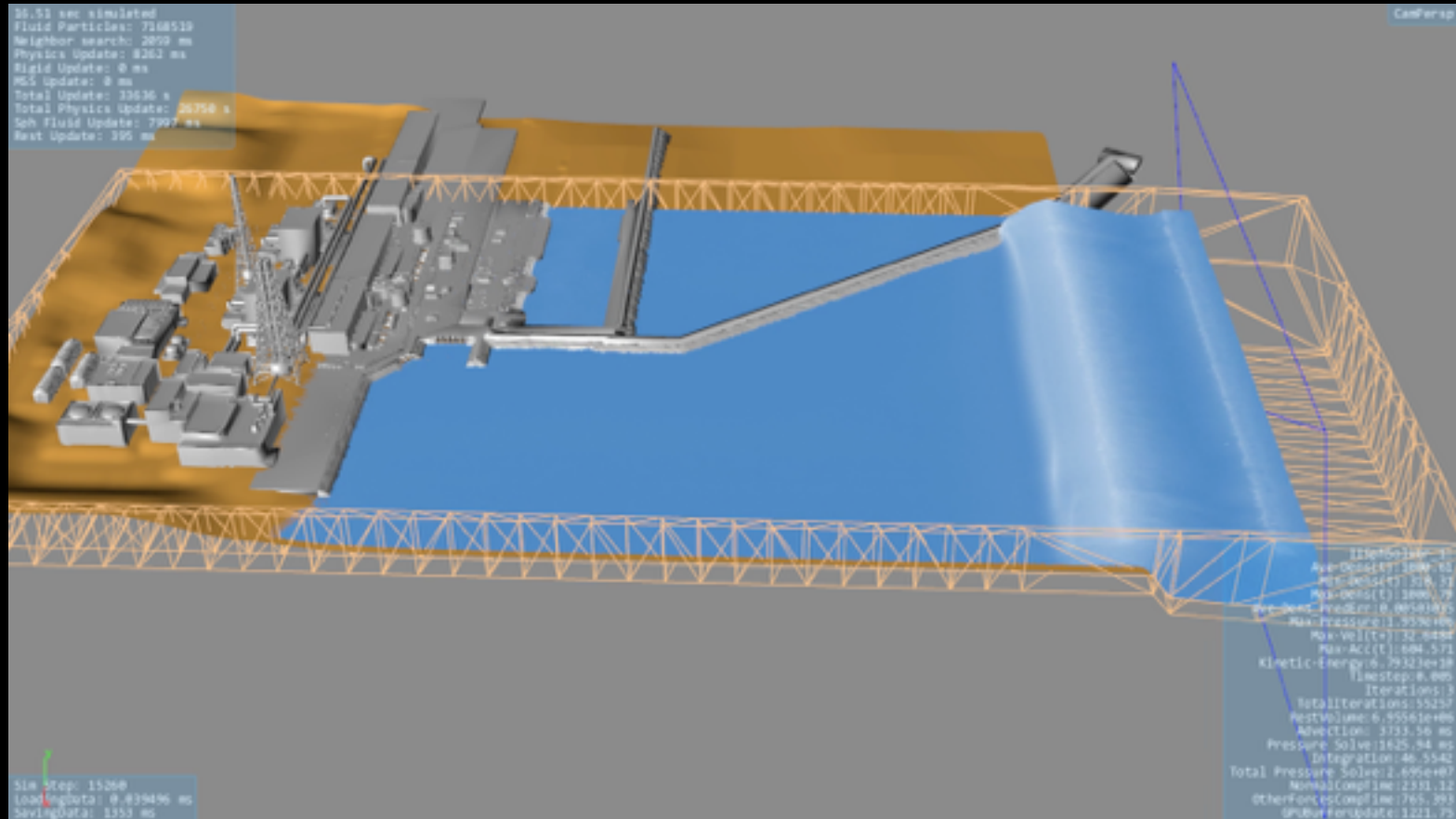
$$\frac{d\rho_i}{dt} = \sum_j m_j (\mathbf{v}_i - \mathbf{v}_j) \cdot \nabla W_{ij},$$

- Pressure Forces
 - State Equation based SPH (SESPH)

$$\mathbf{F}_i^p = -m_i \sum_j m_j \left(\frac{p_j}{\rho_j^2} + \frac{p_i}{\rho_i^2} \right) \nabla W_{ij}.$$

- Particle Pressures are computed by Implicit Incompressible SPH method.
- Jacobi method used for solution of this implicit method.

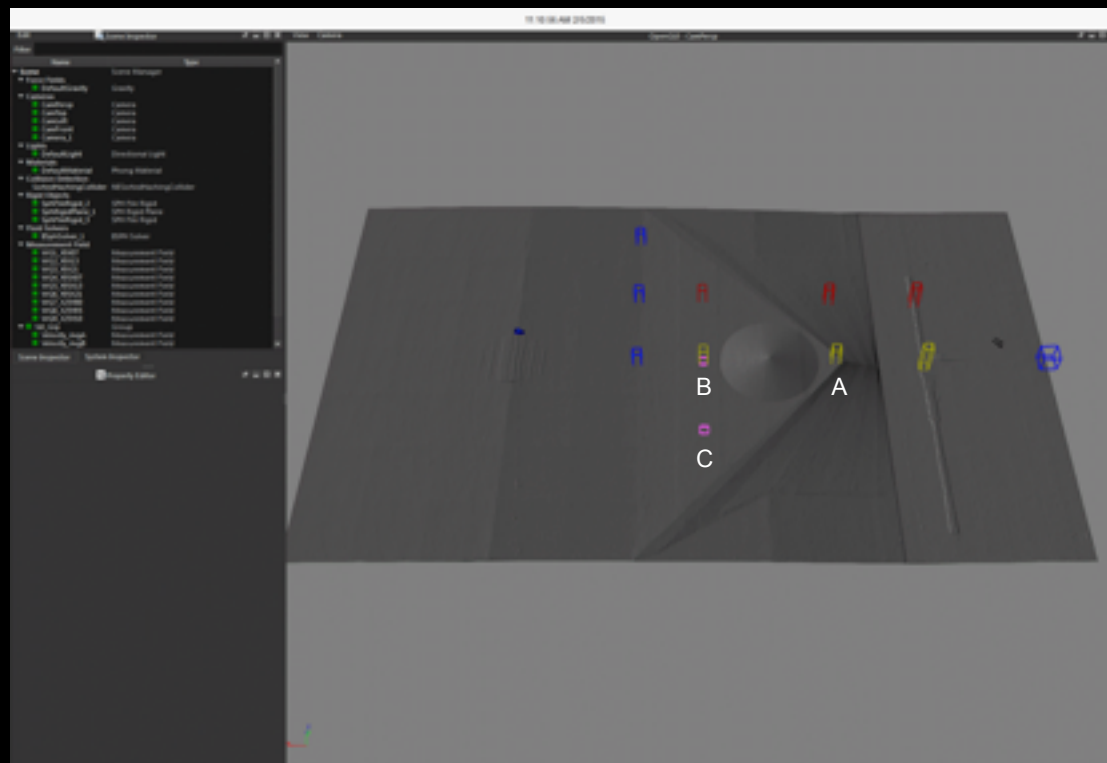
Geo scale



Benchmark Problem 5

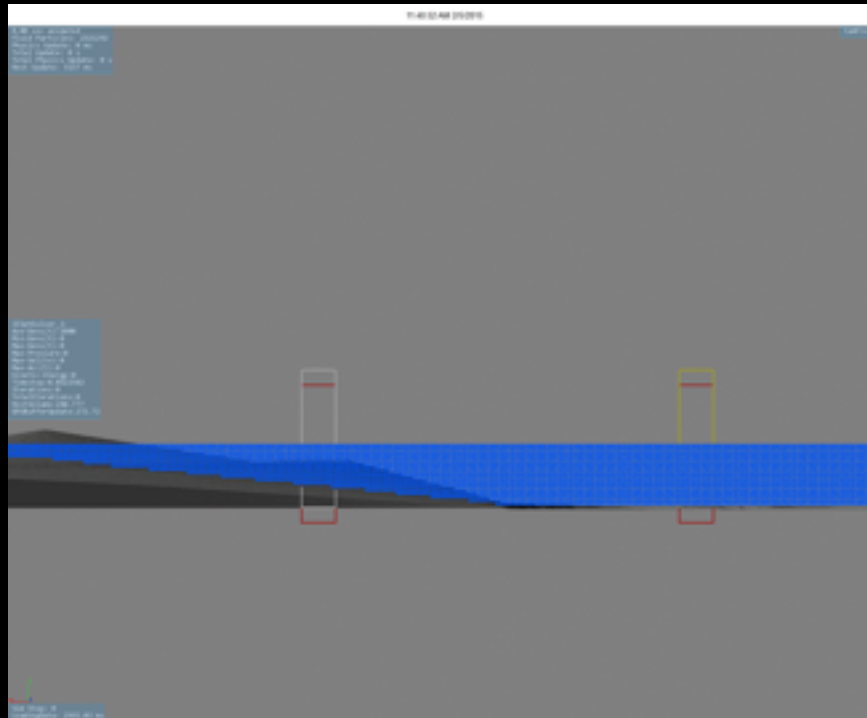
- Setup
 - Terrain geometry bathymetry data
 - Setup of Initial Conditions (Volume fill)
- Simulation
 - Time to settle
 - Paddle Movement
 - Measurement Fields
- Data and Video comparisons
- Discussion

Benchmark Problem 5 - Setup



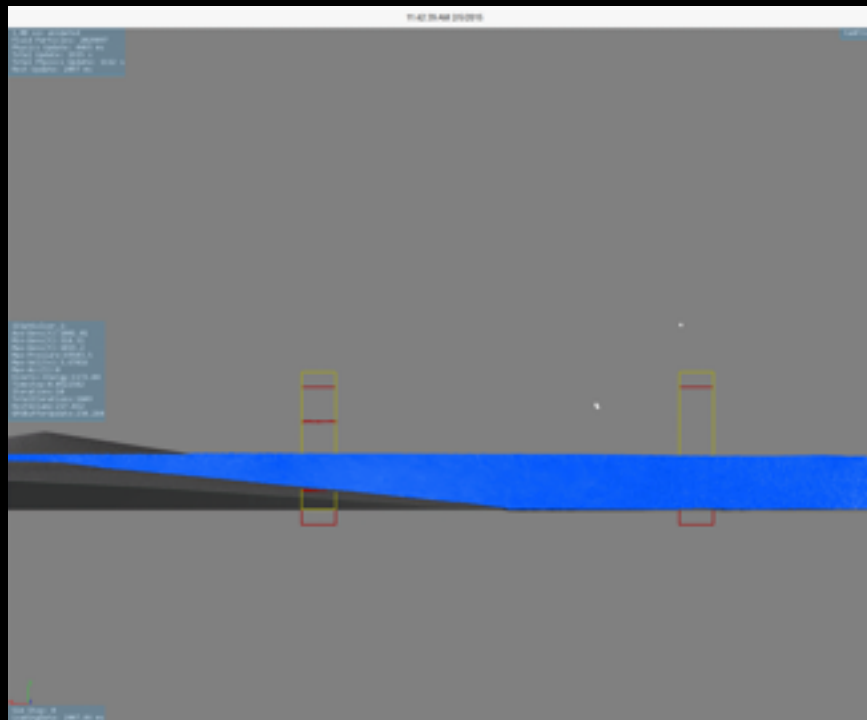
Benchmark Problem 5 - Setup

- Volumetric representation of geometry of water
 - Boolean Operations to remove particles
- Particle overlap removal, settling (87% volume)



Benchmark Problem 5 - Setup

- Volumetric representation of geometry of water
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Wave Piston

- Goring 1978 Wave Model for a Piston wave maker.

Goring (1978) proposed a model for the purpose of laboratory solitary wave generation. The surface profile $\eta(x, t)$ of a solitary wave can be described using the following equation:

$$\eta(x, t) = H \operatorname{sech}^2[\kappa(Ct - X_0)] \quad (\text{B-1})$$

$$C = \sqrt{g(H + h)} \quad (\text{B-2})$$

$$\kappa = \sqrt{3H/4h^3} \quad (\text{B-3})$$

Where C is the wave celerity or phase velocity, X_0 is the wave displacement, H is the wave height and h is the depth of the ocean. Applying equation B-1 to the wave maker piston results in

$$X_0(t) = H/\kappa h (\tanh(\kappa(Ct - X_0))) \quad (\text{B-4})$$

Using this equation one can solve for the wave piston displacement and wave piston duration using newton iterations resulting in

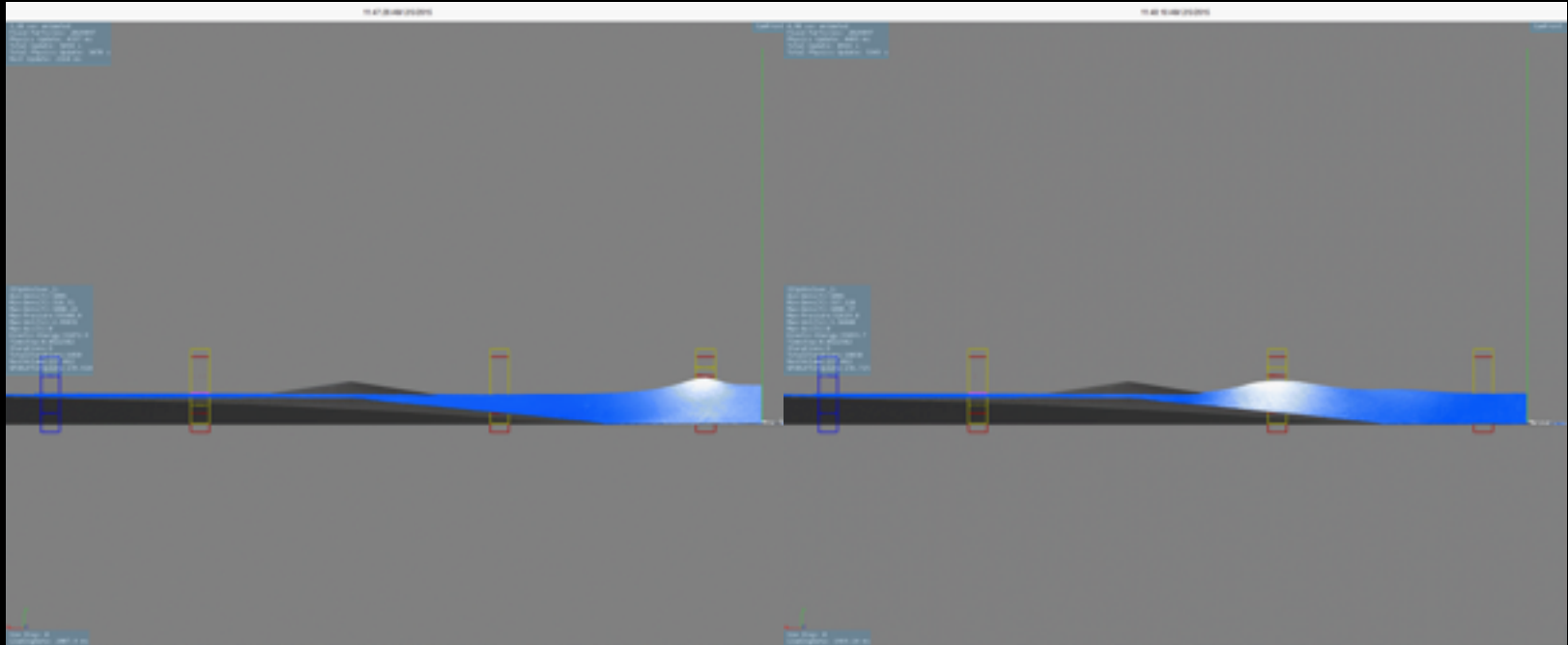
$$S = \sqrt{16Hh/3}$$

and

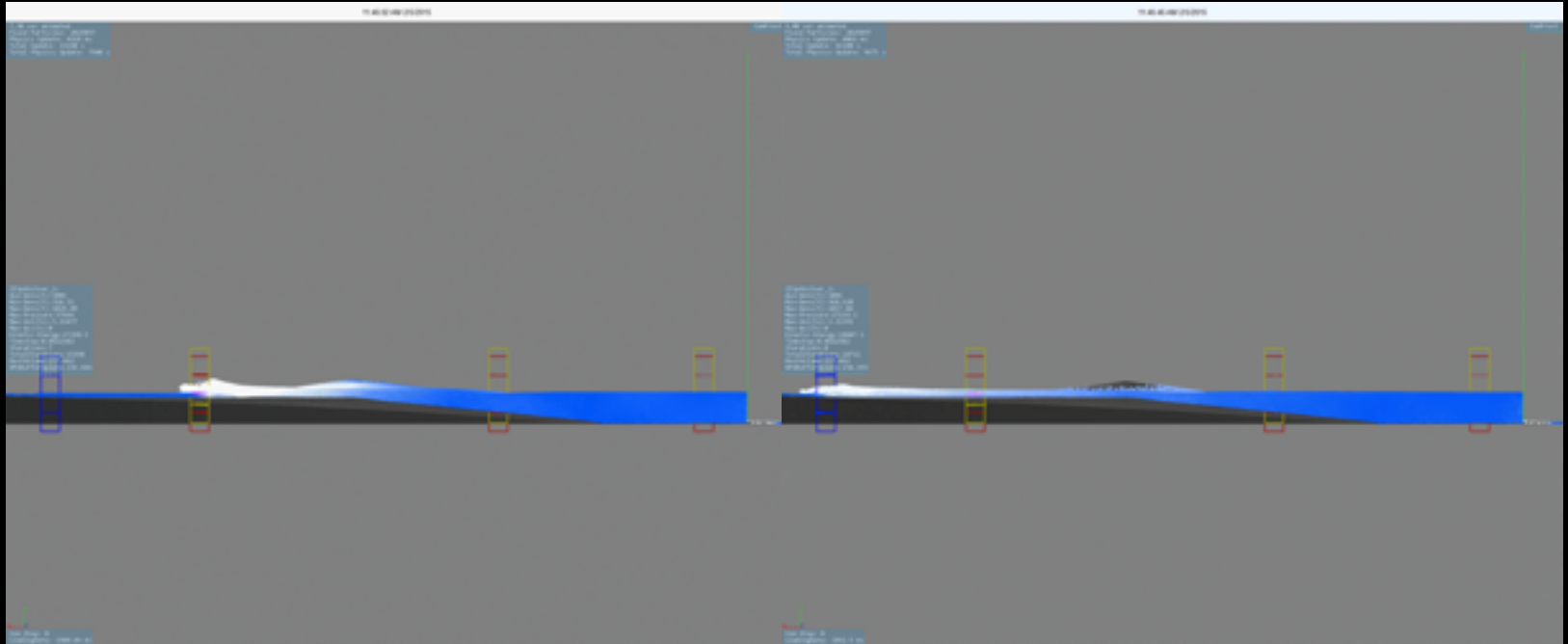
$$t_f = 2(3.80 + H/h)/\kappa C$$

where S is the displacement and t_f is the time taken for it.

Benchmark Problem 5 - Setup

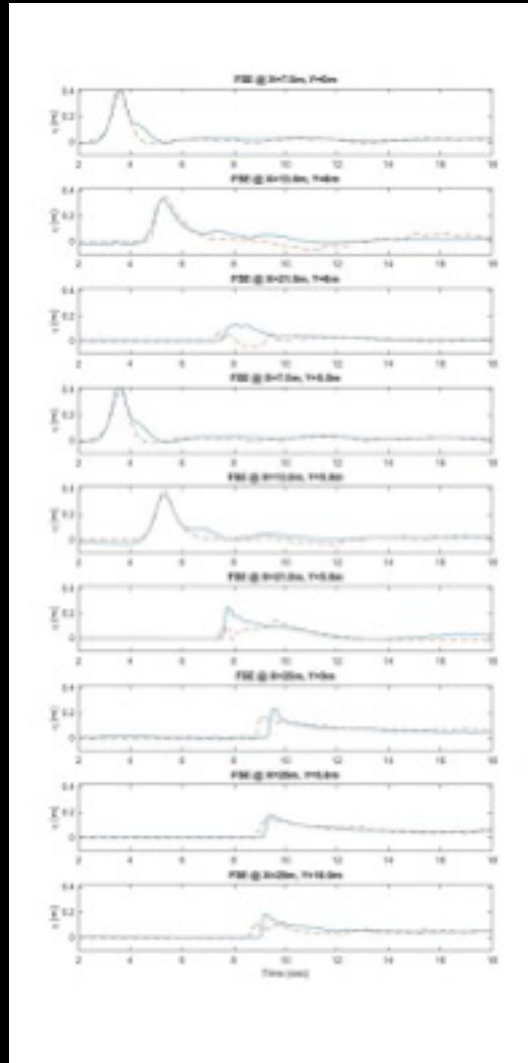


Benchmark Problem 5 - Setup



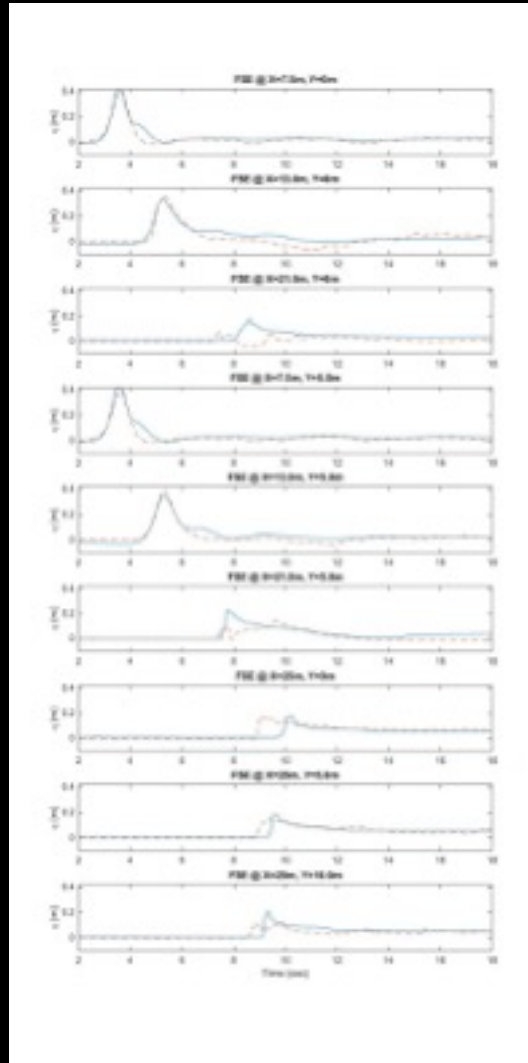
Benchmark Problem 5 - Data

- Roughness parameter 0.002



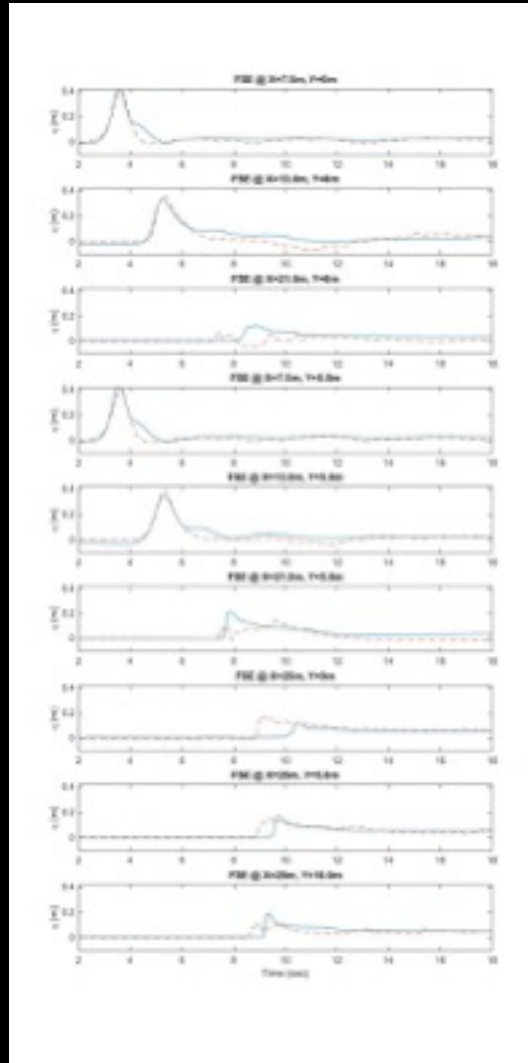
Benchmark Problem 5 - Data

- Roughness parameter 0.003



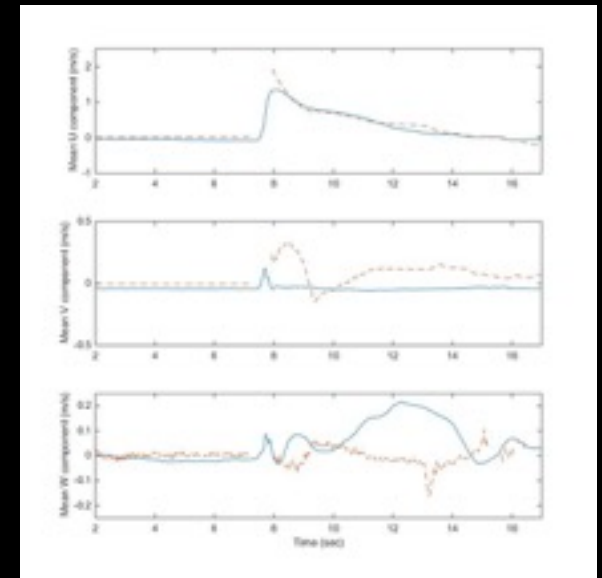
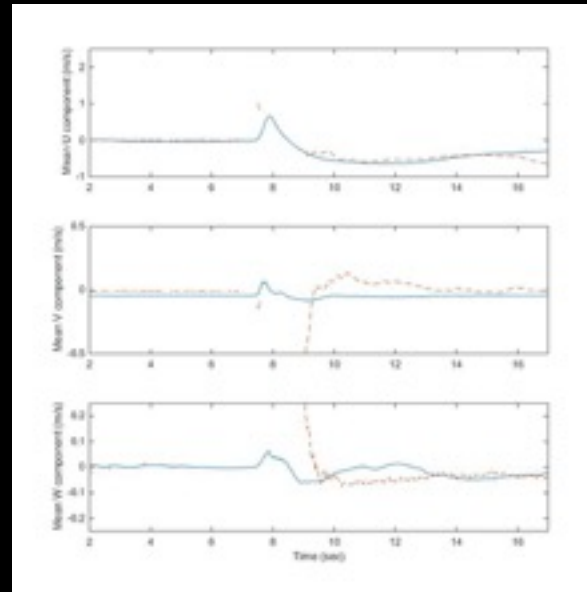
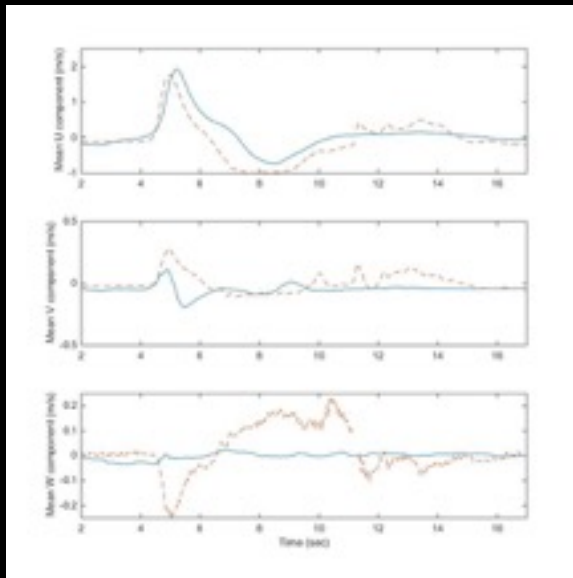
Benchmark Problem 5 - Data

- Roughness parameter 0.009

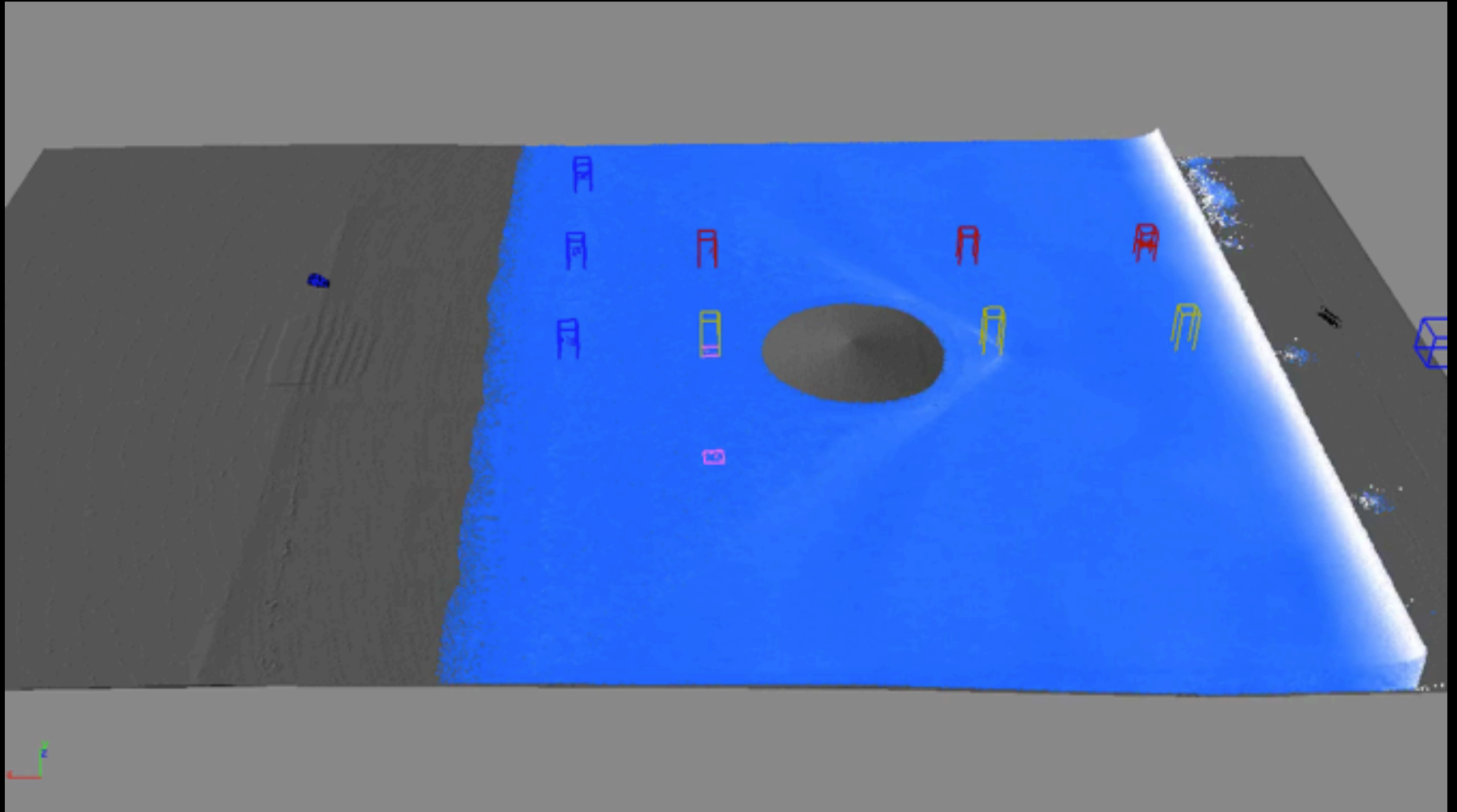


Benchmark Problem 5 - Data

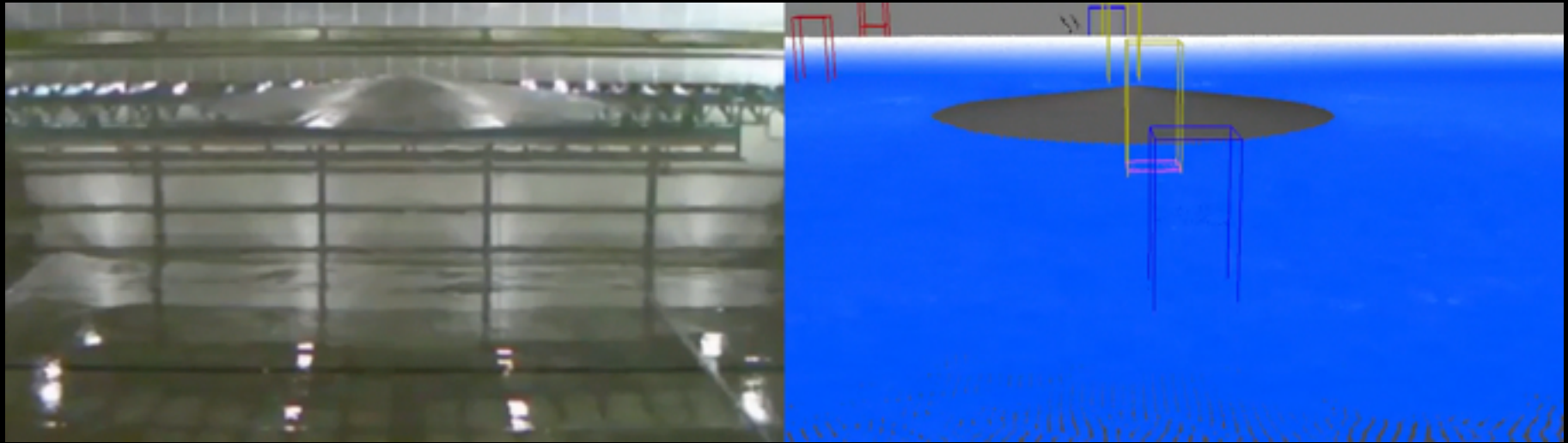
- Roughness parameter 0.002



Benchmark 5 - Video



Benchmark 5 - Video



Benchmark Problem 5 - Discussion

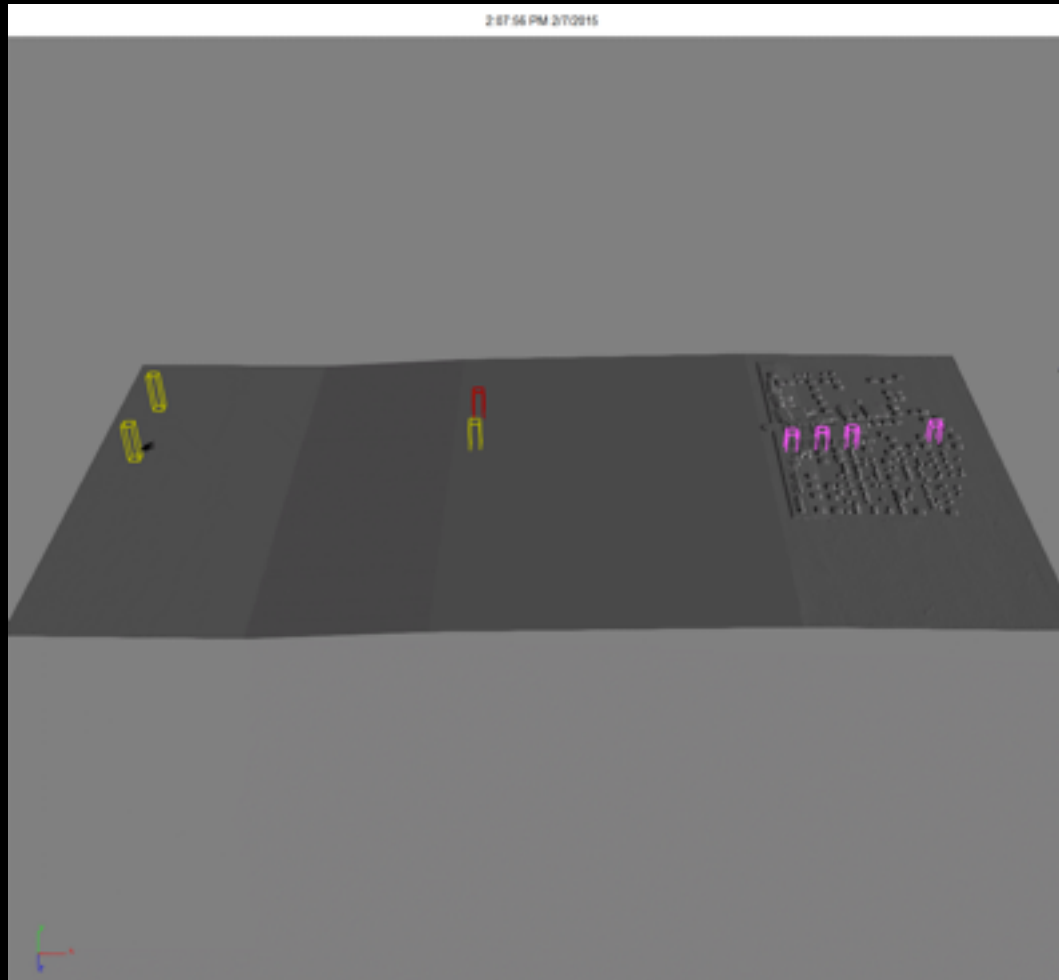
- No Turbulence Modeling
- Roughness based on Artificial Viscosity
 - Research on Manning Coefficient/Artificial Viscosity/Reynolds Number

Benchmark Problem 4

- Setup - Similar to Problem 5
- Simulation
 - Scripted Wave piston movement based on data
- Data and Video comparisons

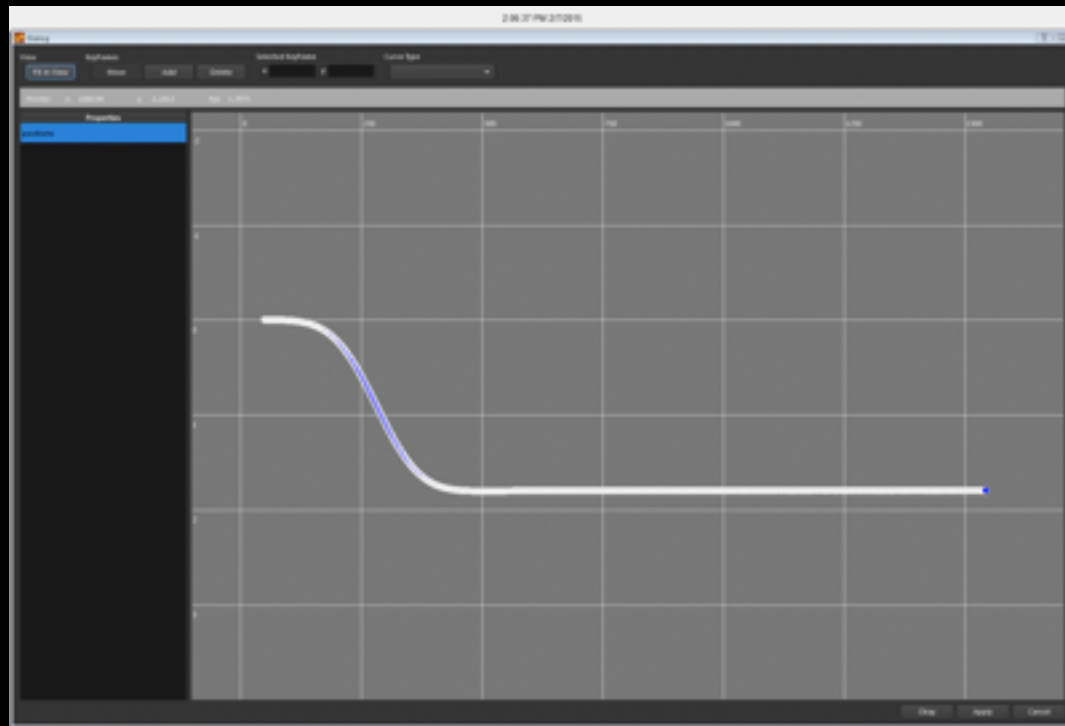
Benchmark Problem 4

- Setup - Terrain



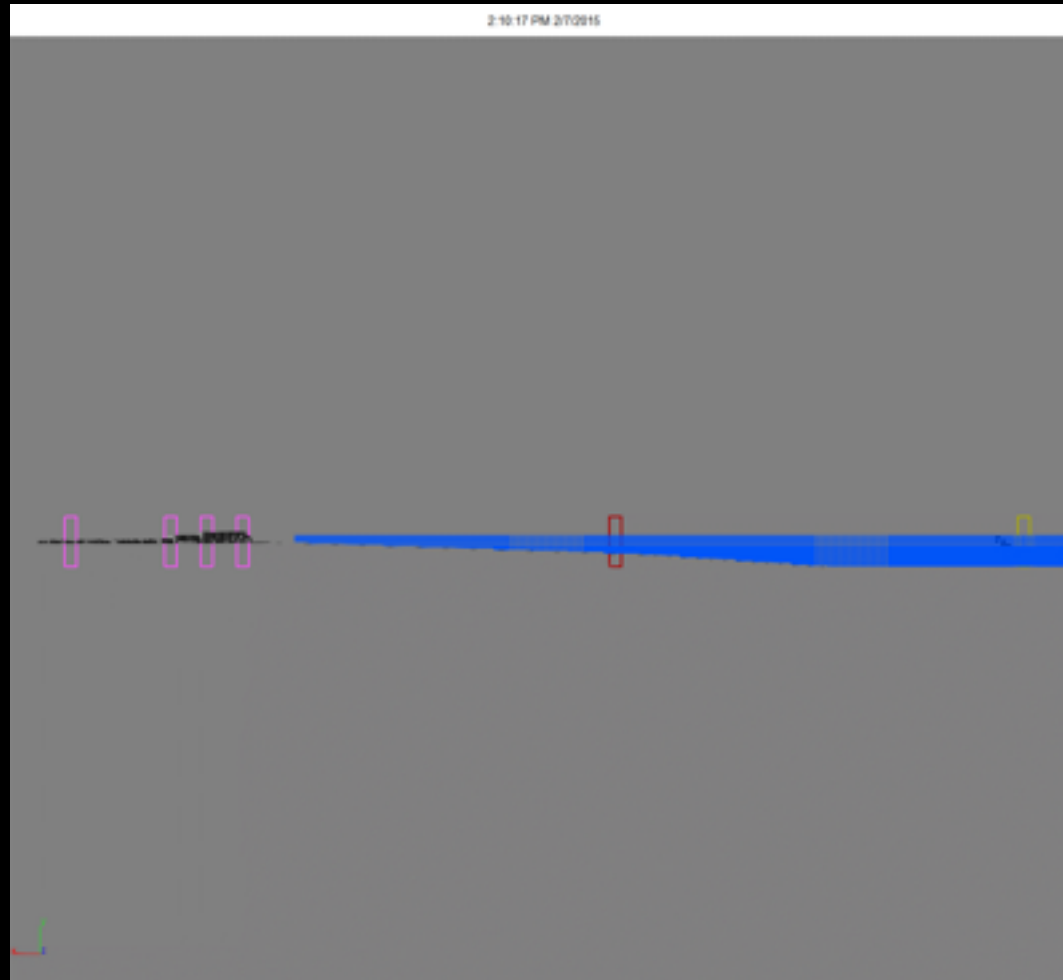
Benchmark Problem 4

- Wave piston movement



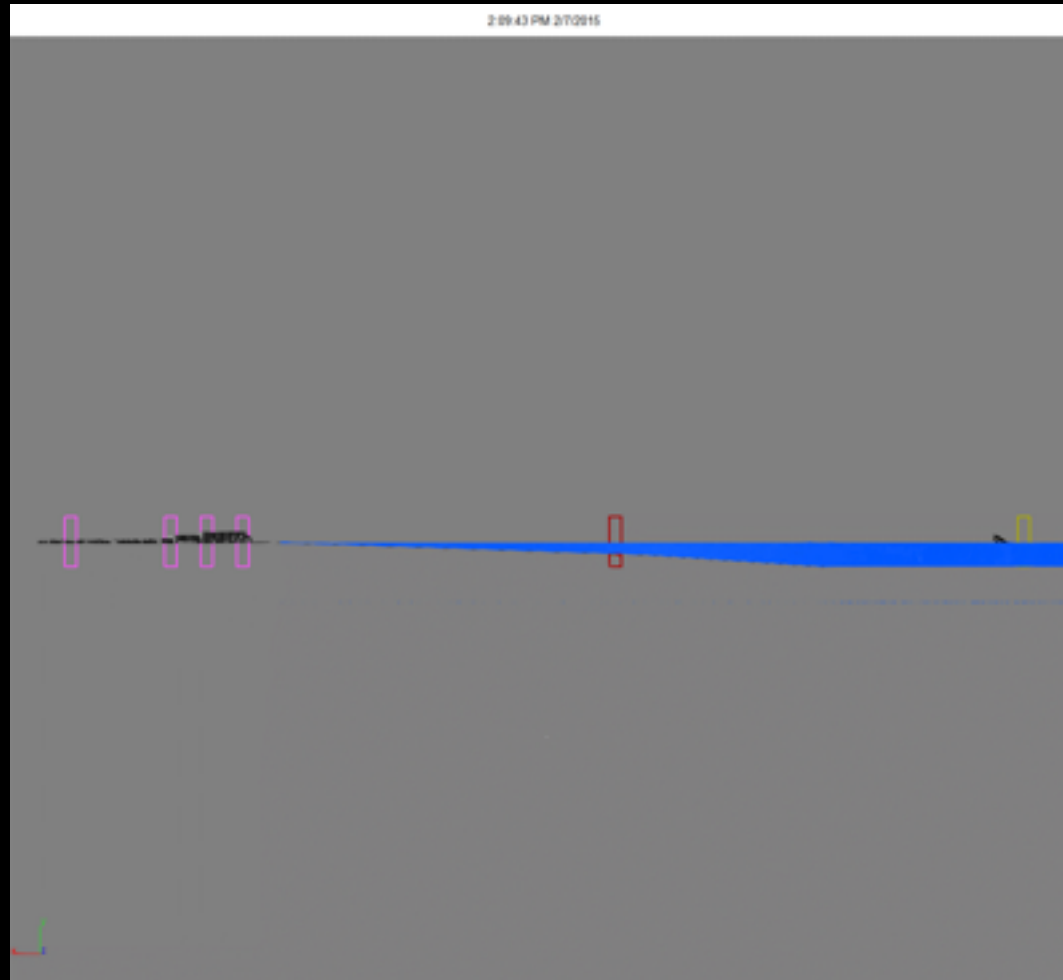
Benchmark Problem 4

- Simulation



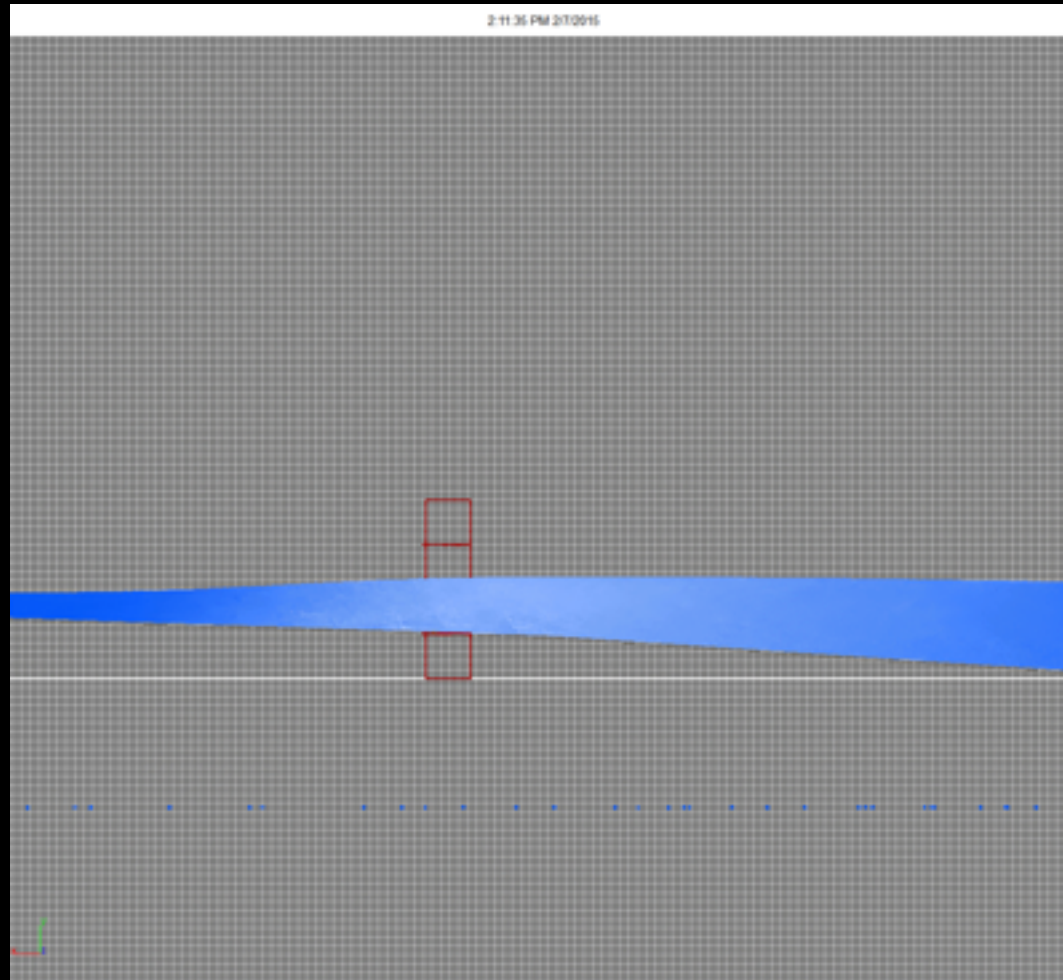
Benchmark Problem 4

- Simulation

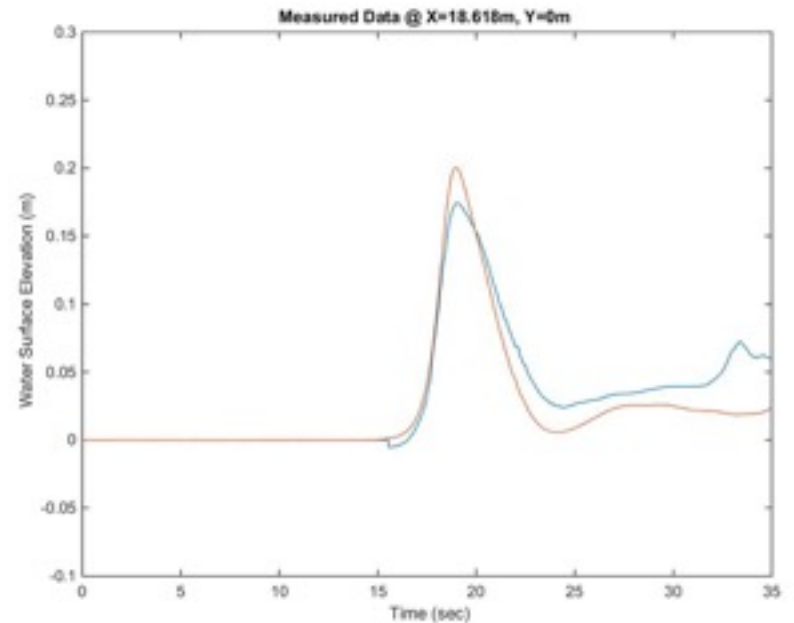
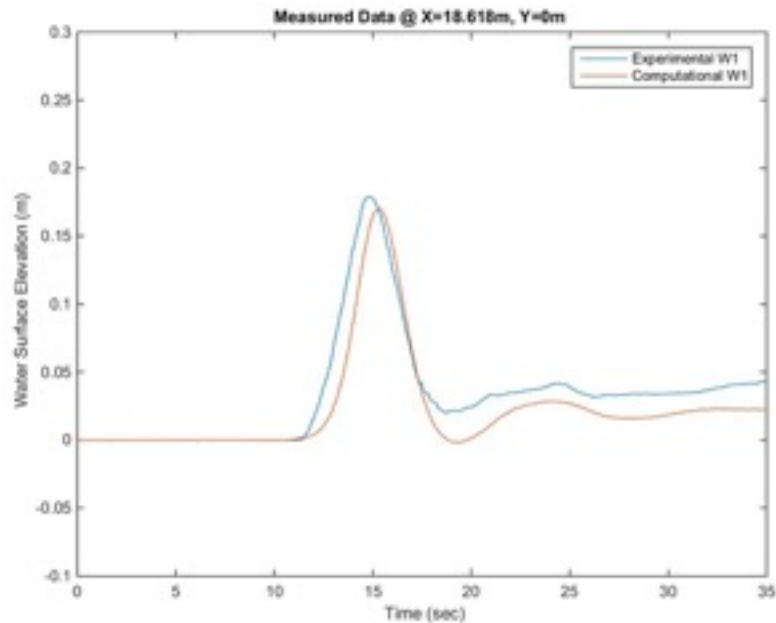


Benchmark Problem 4

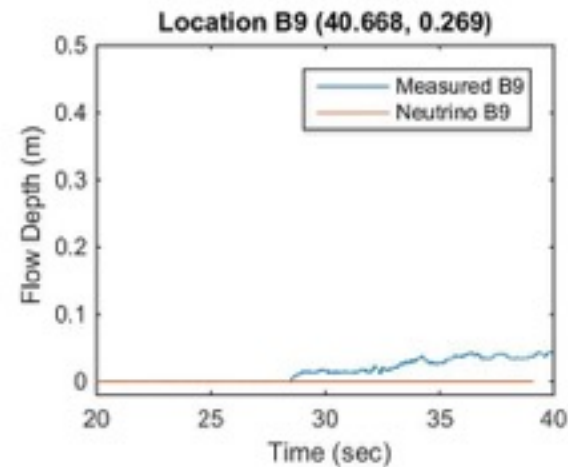
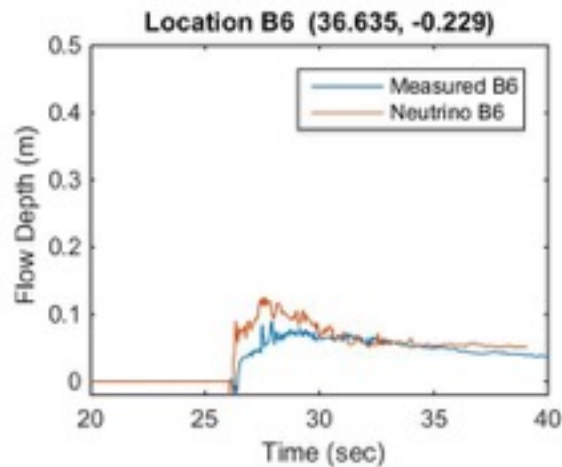
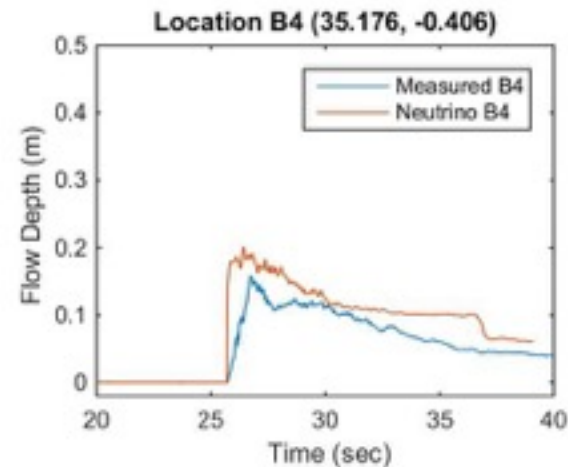
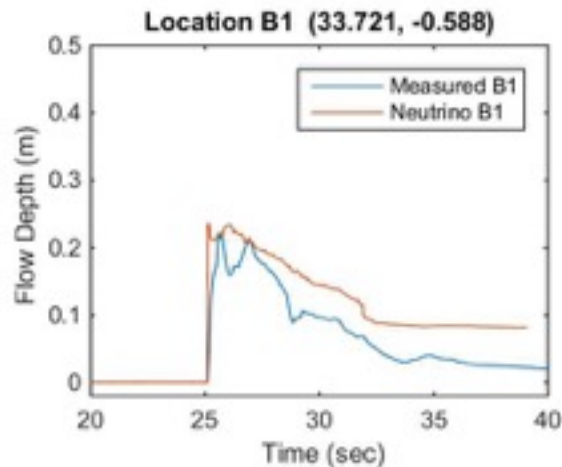
- Simulation



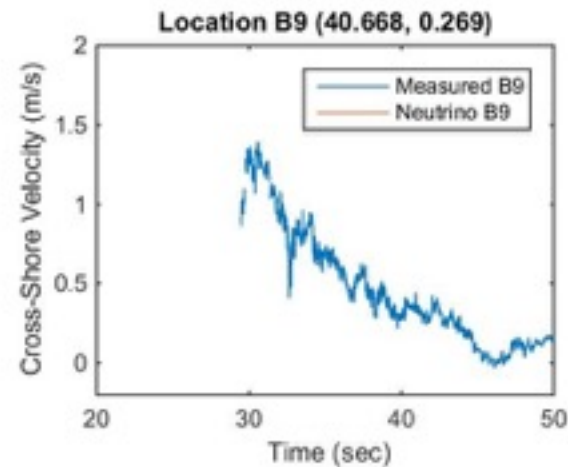
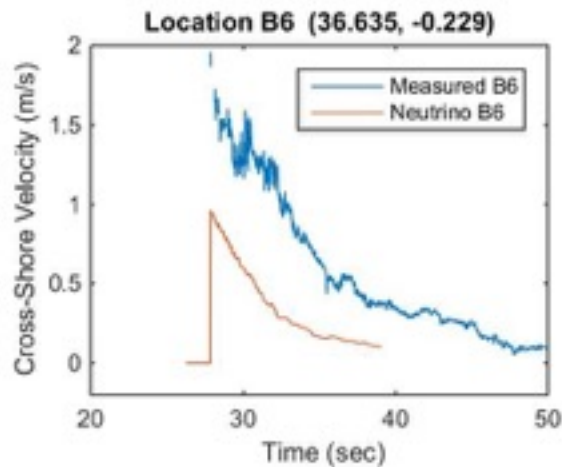
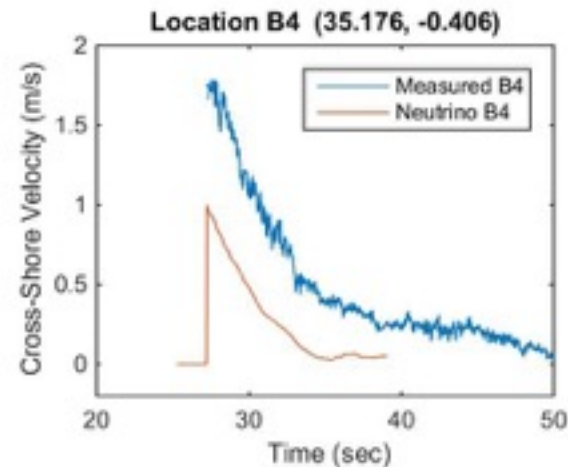
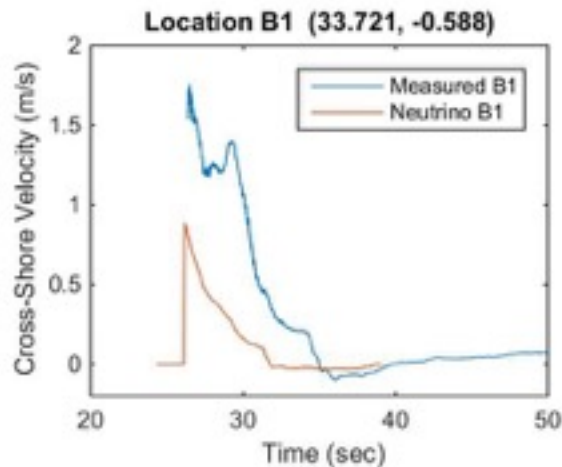
Benchmark Problem 4 - Data



Benchmark Problem 4 - Data



Benchmark Problem 4 - Data



Benchmark Problem 4 - Video



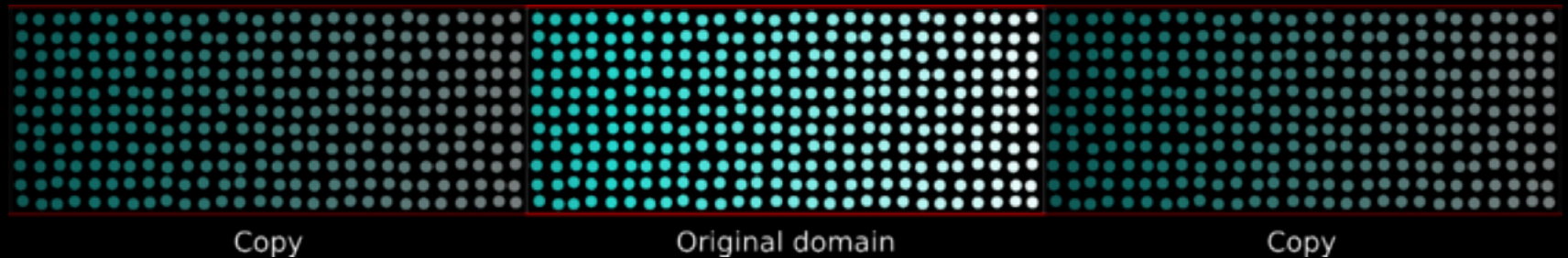
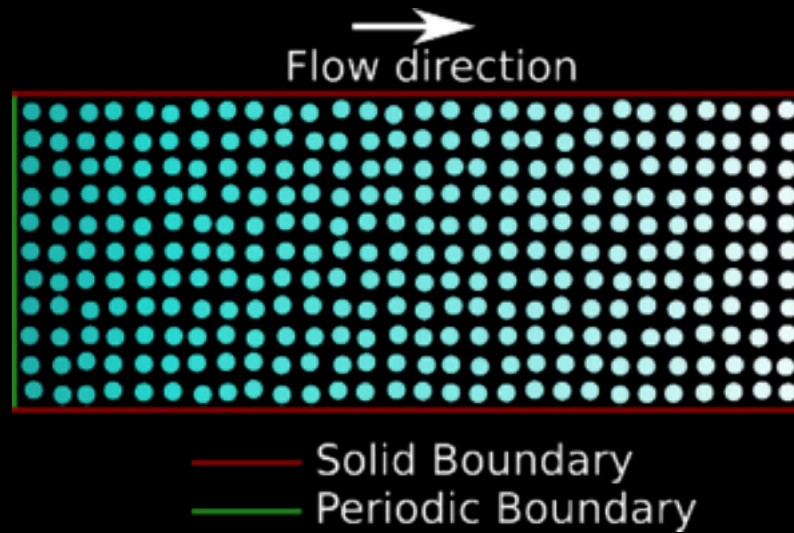
Benchmark Problem 4 - Discussion

- Velocity Profiles
 - Base water height was 0.94m vs 0.97 (problem)
- Roughness coefficient was based on Problem 5
- Momentum flux not yet implemented on measurement

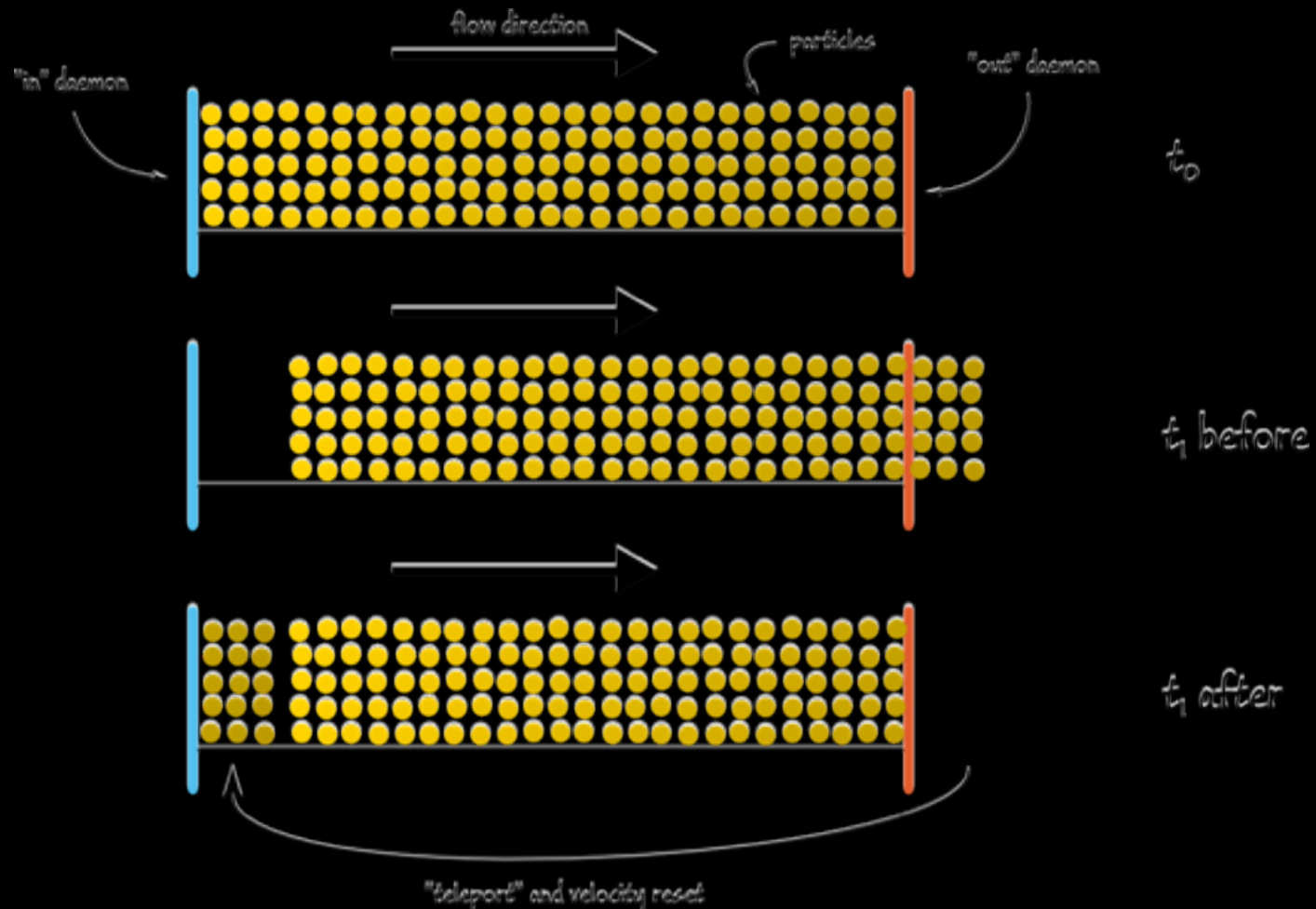
Benchmark Problem 1

- Setup
 - Periodic Boundary Conditions
 - Inflow Velocity set to U
 - Particle Interaction Radius based Passive Domain on either side of the flow boundary
 - Particles exiting the active domain are placed as copies in either side in the passive domain.
- Limitation
 - Roughness Modeling and model Resolution

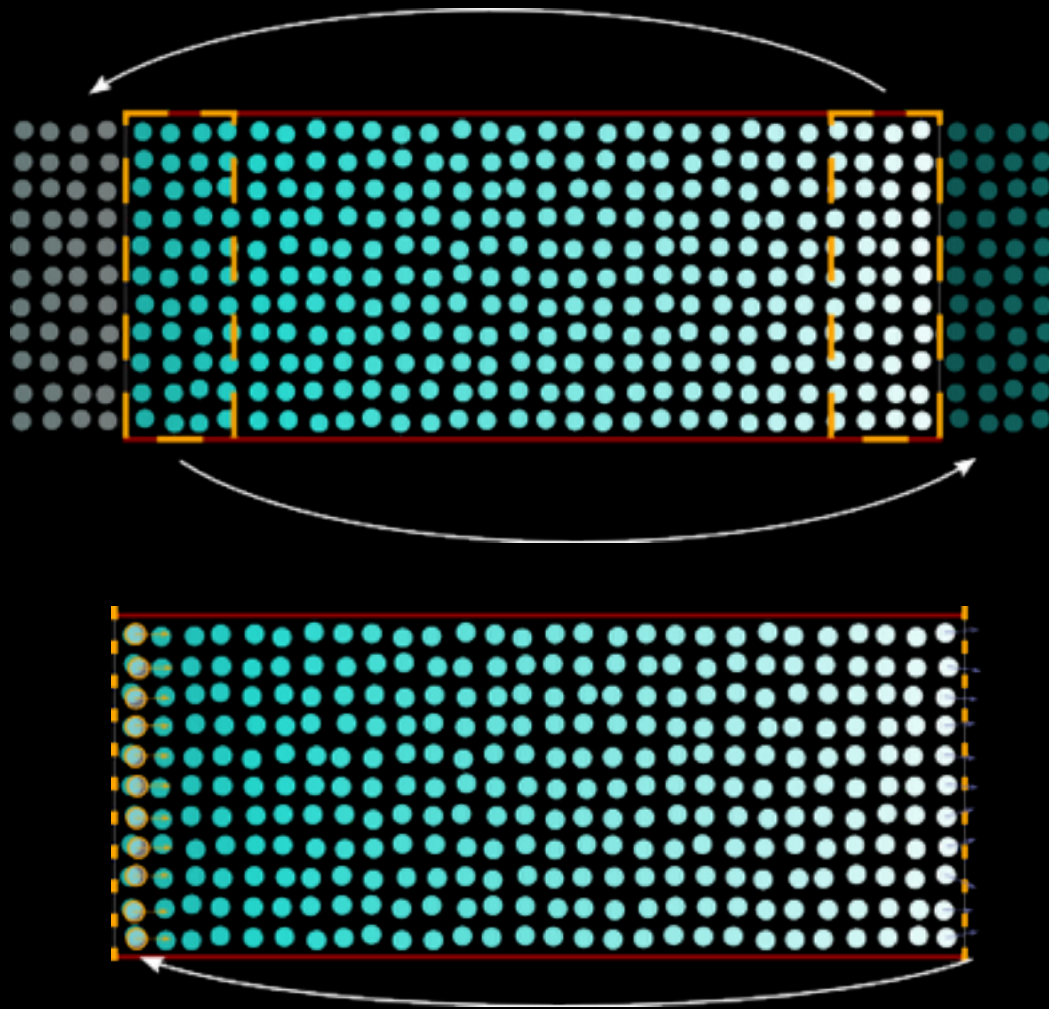
Benchmark Problem 1



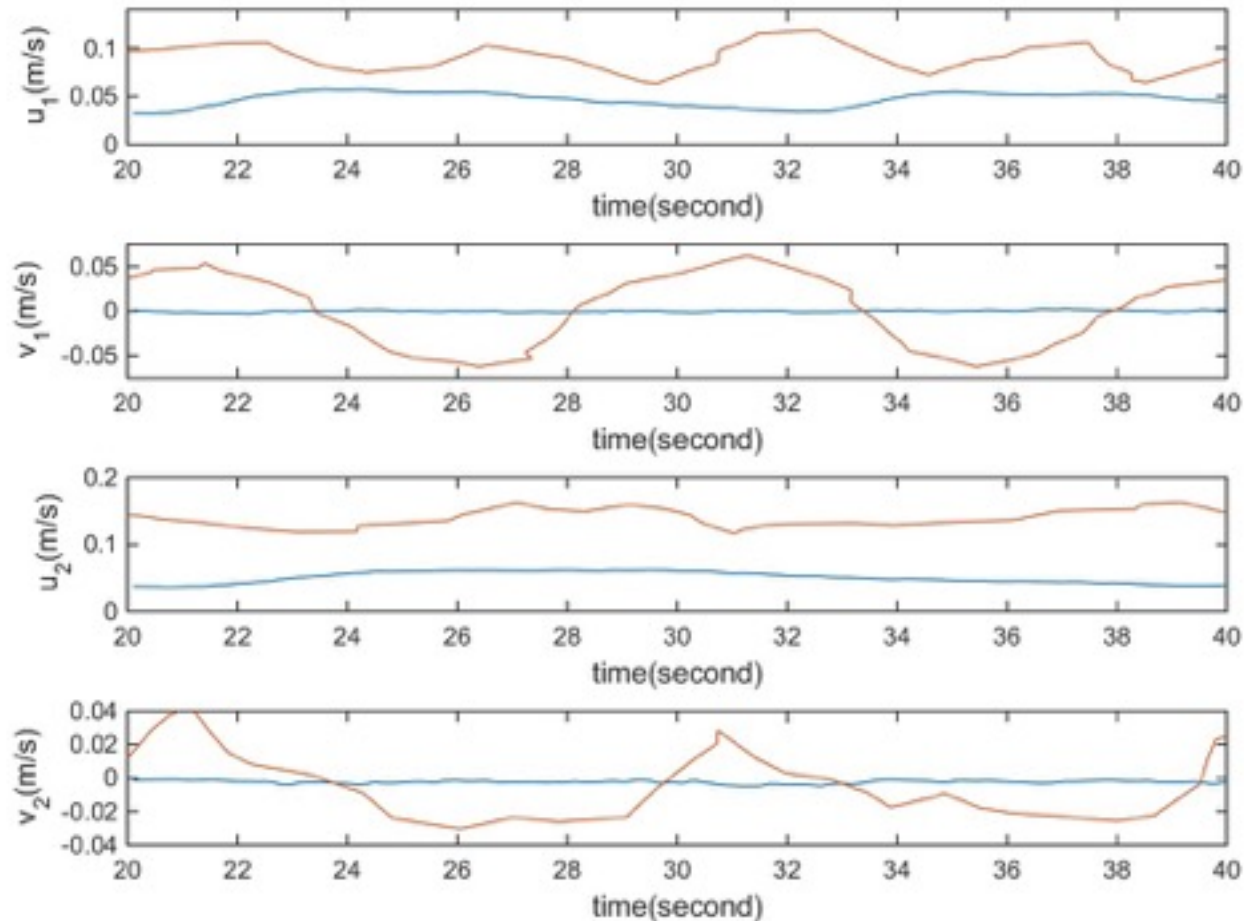
Benchmark Problem 1



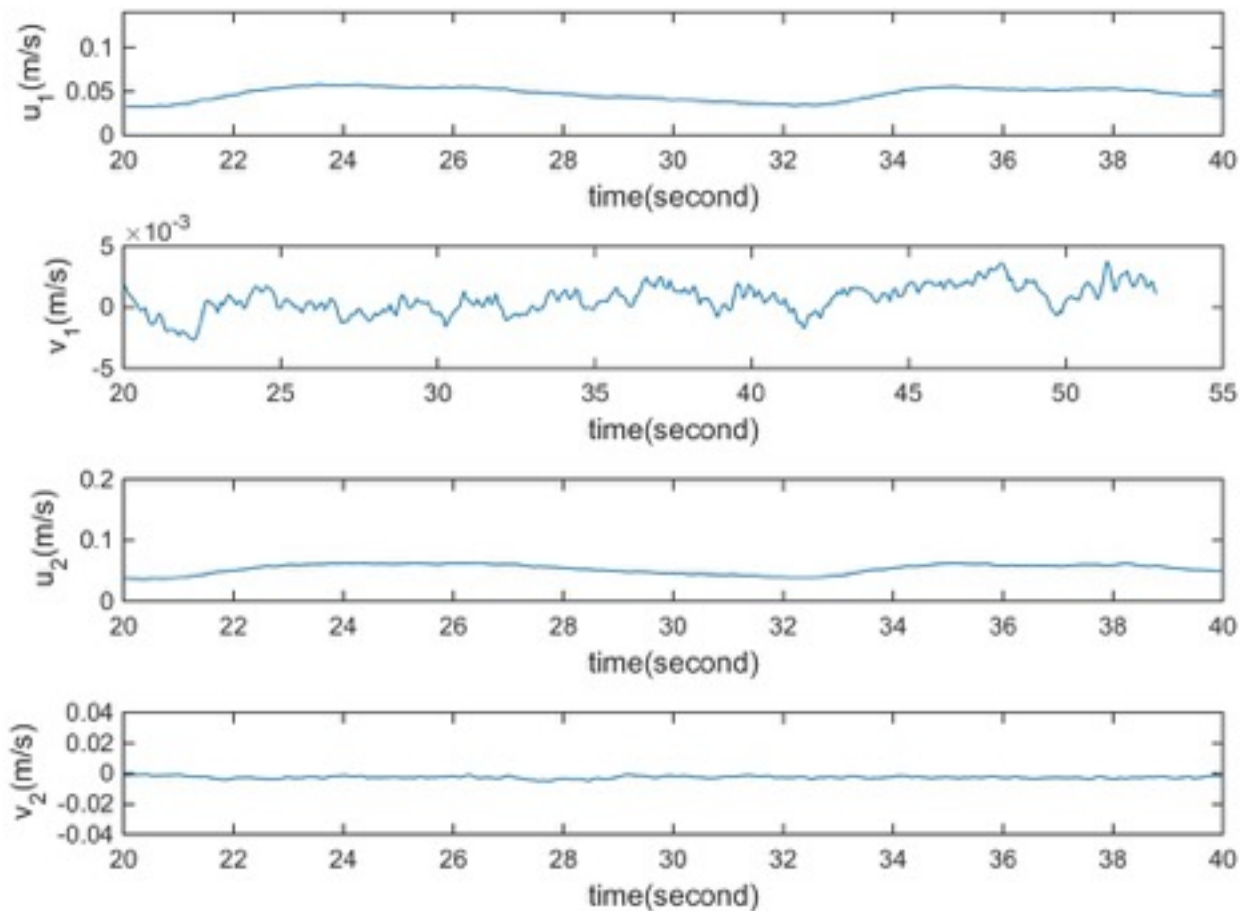
Benchmark Problem 1



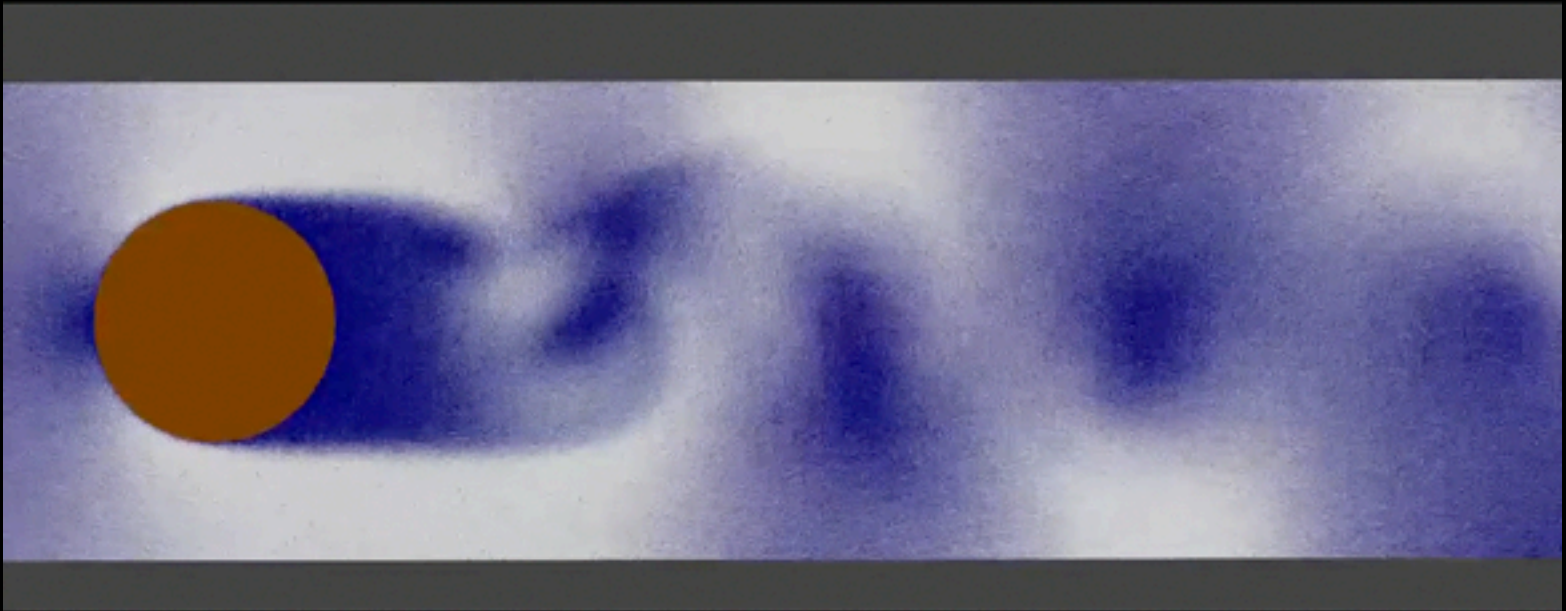
Benchmark Problem 1 - Data



Benchmark Problem 1 - Data



Benchmark Problem 1 - Alt Video

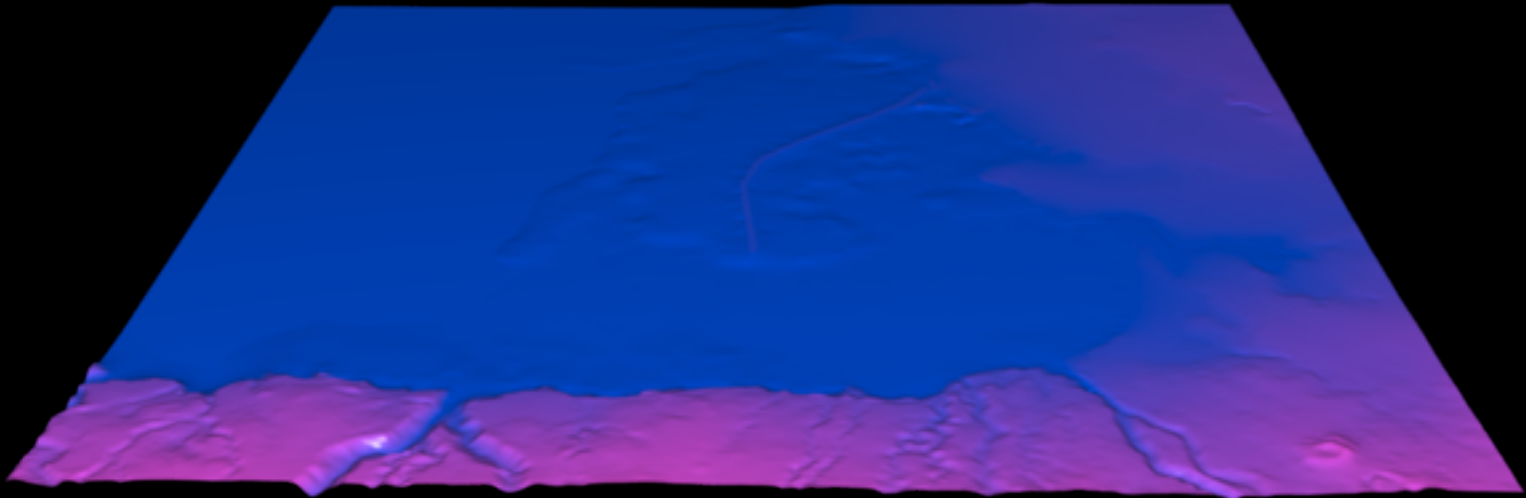


Benchmark Problem 1 - Discussion

- Vorticity not clearly prevalent with this problem domain
- Data didn't match - work needed

Benchmark Problem 2

- Data
 - 7000x7000x2 m
 - 100 Million Particles with 0.5m Res
 - 800 Million Particles with 0.25m Res



- Memory/Computing
 - 128 G Memory with 40 Threads - 1 Min Sim - 96 Hours

Conclusion and Future Work

- Better modeling of solid/fluid friction
- Coupling 2D shallow water simulations with 3D SPH
- Distributed computing to handle large particle count
- Validation in geophysical scale.

Monster Wave



Thanks

- Dr Curtis Smith (INL), Dr Nadir Akinci, Greg Klar